

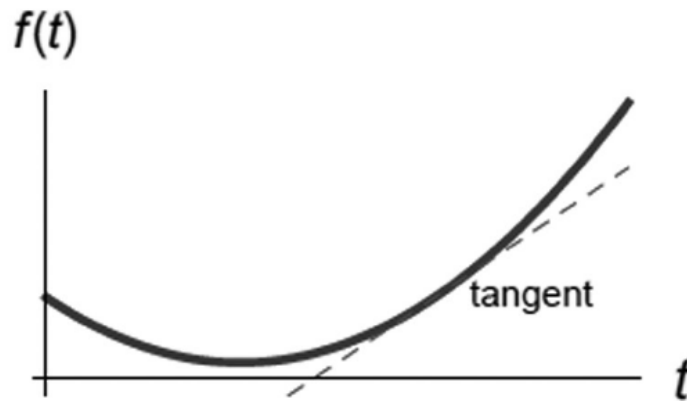
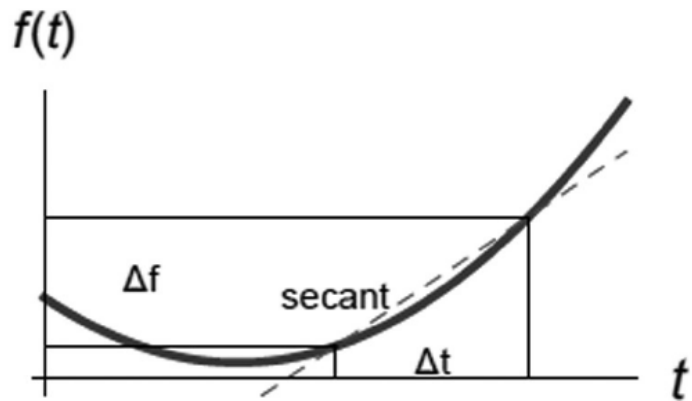
# 4 Calculus

Given the function  $f(x)$ , compute  $d^n f/dx^n$  at given  $x$

Compute  $\int_a^b f(x) dx$ , where  $f(x)$  is a given function

# 4.1 Derivatives

- In mathematics, the rate of change of a function is referred to as the *derivative*.
- For a function of a single variable, the derivative at a given point is the *slope of the tangent*



$$\frac{df}{dt} = \text{derivative of } f(t) \text{ with respect to } t = \lim_{\Delta t \rightarrow 0} \left( \frac{f(t + \Delta t) - f(t)}{\Delta t} \right)$$

**Forward difference form**

$$\frac{df}{dt} = \lim_{\Delta t \rightarrow 0} \left( \frac{f(t + \Delta t / 2) - f(t - \Delta t / 2)}{\Delta t} \right)$$

**Centered difference form**

$$= \lim_{\Delta t \rightarrow 0} \left( \frac{f(t) - f(t - \Delta t)}{\Delta t} \right)$$

**Backward difference form**

## 4.1 Derivatives

$$v = \frac{dx}{dt} = \lim_{\Delta t \rightarrow 0} \left( \frac{x(t + \Delta t) - x(t)}{\Delta t} \right)$$

where

$v$  is velocity

$x$  is position

$t$  is time

**Velocity from Displacement**

$$\frac{d}{dt} (f(z(t))) = \frac{df}{dz} \cdot \frac{dz}{dt}$$

**Chain rule**

$$\frac{d(f \cdot g)}{dt} = f \frac{dg}{dt} + g \frac{df}{dt}$$

**Product rule**

$$\frac{d(t^n)}{dt} = n \cdot t^{n-1}$$

**Derivative of  $t^n$**

**Partial Derivatives**

$$\frac{\partial f}{\partial x} = \lim_{\Delta x \rightarrow 0} \left( \frac{f(x + \Delta x, y) - f(x, y)}{\Delta x} \right)$$

$$\frac{\partial f}{\partial y} = \lim_{\Delta y \rightarrow 0} \left( \frac{f(x, y + \Delta y) - f(x, y)}{\Delta y} \right)$$

## 4.2 Numerical Differentiation

- The derivation of the finite difference approximations for the derivatives of  $f(x)$  are based on forward and backward Taylor series expansions of  $f(x)$  about  $x$ , such as

$$f(x+h) = f(x) + hf'(x) + \frac{h^2}{2!}f''(x) + \frac{h^3}{3!}f'''(x) + \frac{h^4}{4!}f^{(4)}(x) + \dots \quad (\text{a})$$

$$f(x-h) = f(x) - hf'(x) + \frac{h^2}{2!}f''(x) - \frac{h^3}{3!}f'''(x) + \frac{h^4}{4!}f^{(4)}(x) - \dots \quad (\text{b})$$

$$f(x+2h) = f(x) + 2hf'(x) + \frac{(2h)^2}{2!}f''(x) + \frac{(2h)^3}{3!}f'''(x) \quad (\text{c})$$

$$+ \frac{(2h)^4}{4!}f^{(4)}(x) + \dots$$

$$f(x-2h) = f(x) - 2hf'(x) + \frac{(2h)^2}{2!}f''(x) - \frac{(2h)^3}{3!}f'''(x) \quad (\text{d})$$

$$+ \frac{(2h)^4}{4!}f^{(4)}(x) - \dots$$

$$f(x+h) + f(x-h) = 2f(x) + h^2f''(x) + \frac{h^4}{12}f^{(4)}(x) + \dots \quad (\text{e})$$

$$f(x+h) - f(x-h) = 2hf'(x) + \frac{h^3}{3}f'''(x) + \dots \quad (\text{f})$$

$$f(x+2h) + f(x-2h) = 2f(x) + 4h^2f''(x) + \frac{4h^4}{3}f^{(4)}(x) + \dots \quad (\text{g})$$

$$f(x+2h) - f(x-2h) = 4hf'(x) + \frac{8h^3}{3}f'''(x) + \dots \quad (\text{h})$$

- Equations (a)–(h) can be viewed as simultaneous equations that can be solved for various derivatives of  $f(x)$ .

## 4.2 Numerical Differentiation

### Coefficients of central finite difference approximations of $O(h^2)$

	$f(x - 2h)$	$f(x - h)$	$f(x)$	$f(x + h)$	$f(x + 2h)$
$2hf'(x)$		-1	0	1	
$h^2 f''(x)$		1	-2	1	
$2h^3 f'''(x)$	-1	2	0	-2	1
$h^4 f^{(4)}(x)$	1	-4	6	-4	1

### Coefficients of forward finite difference approximations of $O(h)$

	$f(x)$	$f(x + h)$	$f(x + 2h)$	$f(x + 3h)$	$f(x + 4h)$
$hf'(x)$	-1	1			
$h^2 f''(x)$	1	-2	1		
$h^3 f'''(x)$	-1	3	-3	1	
$h^4 f^{(4)}(x)$	1	-4	6	-4	1

### Coefficients of backward finite difference approximations of $O(h)$

	$f(x - 4h)$	$f(x - 3h)$	$f(x - 2h)$	$f(x - h)$	$f(x)$
$hf'(x)$				-1	1
$h^2 f''(x)$			1	-2	1
$h^3 f'''(x)$		-1	3	-3	1
$h^4 f^{(4)}(x)$	1	-4	6	-4	1

Truncation error is now  $O(h)$ , which is not as good as the  $O(h^2)$  error in central difference approximations.

## 4.2 Numerical Differentiation

### Coefficients of central finite difference approximations of $O(h^2)$

	$f(x - 2h)$	$f(x - h)$	$f(x)$	$f(x + h)$	$f(x + 2h)$
$2hf'(x)$		-1	0	1	
$h^2 f''(x)$		1	-2	1	
$2h^3 f'''(x)$	-1	2	0	-2	1
$h^4 f^{(4)}(x)$	1	-4	6	-4	1

### Coefficients of forward finite difference approximations of $O(h^2)$

	$f(x)$	$f(x + h)$	$f(x + 2h)$	$f(x + 3h)$	$f(x + 4h)$	$f(x + 5h)$
$2hf'(x)$	-3	4	-1			
$h^2 f''(x)$	2	-5	4	-1		
$2h^3 f'''(x)$	-5	18	-24	14	-3	
$h^4 f^{(4)}(x)$	3	-14	26	-24	11	-2

### Coefficients of backward finite difference approximations of $O(h^2)$

	$f(x - 5h)$	$f(x - 4h)$	$f(x - 3h)$	$f(x - 2h)$	$f(x - h)$	$f(x)$
$2hf'(x)$				1	-4	3
$h^2 f''(x)$			-1	4	-5	2
$2h^3 f'''(x)$		3	-14	24	-18	5
$h^4 f^{(4)}(x)$	-2	11	-24	26	-14	3

Noncentral Finite Difference Approximations result in  $O(h^2)$  error.

## 4.2 Numerical Differentiation: Example

Given the evenly spaced data points

$x$	0	0.1	0.2	0.3	0.4
$f(x)$	0.0000	0.0819	0.1341	0.1646	0.1797

compute  $f'(x)$  and  $f''(x)$  at  $x = 0$  and  $0.2$  using finite difference approximations of  $\mathcal{O}(h^2)$ .

**Solution** From the forward difference formulas in Table 5.3a, we get

$$f'(0) = \frac{-3f(0) + 4f(0.1) - f(0.2)}{2(0.1)} = \frac{-3(0) + 4(0.0819) - 0.1341}{0.2} = 0.967$$

$$\begin{aligned} f''(0) &= \frac{2f(0) - 5f(0.1) + 4f(0.2) - f(0.3)}{(0.1)^2} \\ &= \frac{2(0) - 5(0.0819) + 4(0.1341) - 0.1646}{(0.1)^2} = -3.77 \end{aligned}$$

The central difference approximations in Table 5.1 yield

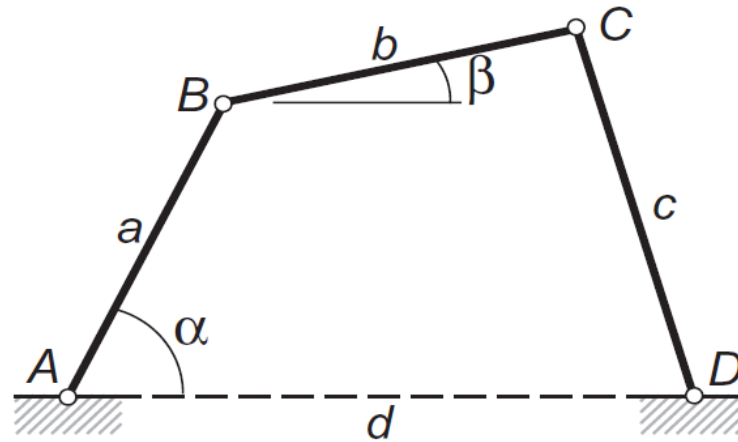
$$f'(0.2) = \frac{-f(0.1) + f(0.3)}{2(0.1)} = \frac{-0.0819 + 0.1646}{0.2} = 0.4135$$

$$f''(0.2) = \frac{f(0.1) - 2f(0.2) + f(0.3)}{(0.1)^2} = \frac{0.0819 - 2(0.1341) + 0.1646}{(0.1)^2} = -2.17$$

	$f(x - 2h)$	$f(x - h)$	$f(x)$	$f(x + h)$	$f(x + 2h)$
$2hf'(x)$		-1	0	1	
$h^2 f''(x)$		1	-2	1	
$2h^3 f'''(x)$	-1	2	0	-2	1
$h^4 f^{(4)}(x)$	1	-4	6	-4	1

	$f(x)$	$f(x + h)$	$f(x + 2h)$	$f(x + 3h)$	$f(x + 4h)$	$f(x + 5h)$
$2hf'(x)$	-3	4	-1			
$h^2 f''(x)$	2	-5	4	-1		
$2h^3 f'''(x)$	-5	18	-24	14	-3	
$h^4 f^{(4)}(x)$	3	-14	26	-24	11	-2

## 4.2 Numerical Differentiation: Example



The linkage shown has the dimensions  $a = 100$  mm,  $b = 120$  mm,  $c = 150$  mm, and  $d = 180$  mm. It can be shown by geometry that the relationship between the angles  $\alpha$  and  $\beta$  is

$$(d - a \cos \alpha - b \cos \beta)^2 + (a \sin \alpha + b \sin \beta)^2 - c^2 = 0$$

For a given value of  $\alpha$ , we can solve this transcendental equation for  $\beta$  by one of the root-finding methods

$\alpha$ (deg)	0	5	10	15	20	25	30
$\beta$ (rad)	1.6595	1.5434	1.4186	1.2925	1.1712	1.0585	0.9561

If link  $AB$  rotates with the constant angular velocity of 25 rad/s, use finite difference approximations of  $\mathcal{O}(h^2)$  to tabulate the angular velocity  $d\beta/dt$  of link  $BC$  against  $\alpha$ .



## 4.2 Numerical Differentiation: Example

**Solution** The angular speed of  $BC$  is

$$\frac{d\beta}{dt} = \frac{d\beta}{d\alpha} \frac{d\alpha}{dt} = 25 \frac{d\beta}{d\alpha} \text{ rad/s}$$

where  $d\beta/d\alpha$  is computed from finite difference approximations using the data in the table. Forward and backward differences of  $\mathcal{O}(h^2)$  are used at the endpoints, central differences elsewhere. Note that the increment of  $\alpha$  is

$$h = (5 \text{ deg}) \left( \frac{\pi}{180} \text{ rad / deg} \right) = 0.087266 \text{ rad}$$

The computations yield

$$\dot{\beta}(0^\circ) = 25 \frac{-3\beta(0^\circ) + 4\beta(5^\circ) - \beta(10^\circ)}{2h} = 25 \frac{-3(1.6595) + 4(1.5434) - 1.4186}{2(0.087266)}$$

$$= -32.01 \text{ rad/s}$$

$$\dot{\beta}(5^\circ) = 25 \frac{\beta(10^\circ) - \beta(0^\circ)}{2h} = 25 \frac{1.4186 - 1.6595}{2(0.087266)} = -34.51 \text{ rad/s}$$

and so forth.

The complete set of results is

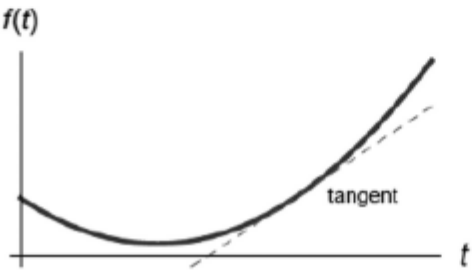
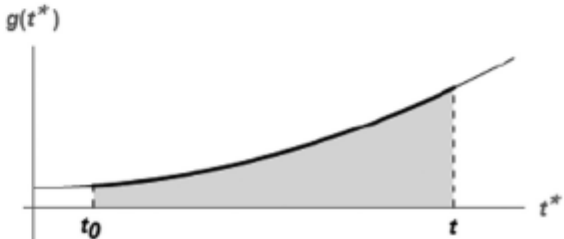
$\alpha$ (deg)	0	5	10	15	20	25	30
$\dot{\beta}$ (rad/s)	-32.01	-34.51	-35.94	-35.44	-33.52	-30.81	-27.86

	$f(x-2h)$	$f(x-h)$	$f(x)$	$f(x+h)$	$f(x+2h)$
$2hf'(x)$		-1	0	1	
$h^2f''(x)$		1	-2	1	
$2h^3f'''(x)$	-1	2	0	-2	1
$h^4f^{(4)}(x)$	1	-4	6	-4	1

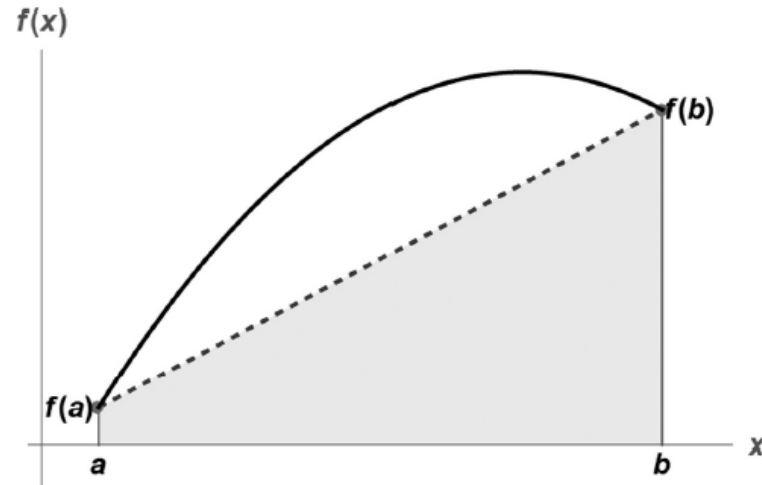
	$f(x)$	$f(x+h)$	$f(x+2h)$	$f(x+3h)$	$f(x+4h)$	$f(x+5h)$
$2hf'(x)$	-3	4	-1			
$h^2f''(x)$	2	-5	4	-1		
$2h^3f'''(x)$	-5	18	-24	14	-3	
$h^4f^{(4)}(x)$	3	-14	26	-24	11	-2

```
alpha=[0:5:30]*pi/180
beta=[1.6595;1.5434;1.4186;1.2925;1.1712;1.0585;0.9561]
dbeta_dt=25*gradient(beta,alpha)
```

## 4.3 Integrals

	Derivatives	Integrals
Concept	<p><i>Differentiation</i> is the process of finding <math>g(t)</math> from <math>f(t)</math>.</p> $\underbrace{g(t)}_{?} = \frac{d\hat{f}}{dt}$	<p><i>Integration</i> is the process of finding the anti-derivative <math>f(t)</math> from <math>g(t)</math>.</p> $\underbrace{g(t)}_{?} = \frac{d\hat{f}}{dt}$
Numerical Approximation	$\frac{df}{dt} \cong \frac{f(t + \Delta t) - f(t)}{\Delta t}$	$f(t) - f(t_1) \cong \sum_{i=1}^n g(t_i)\Delta t$ $t_i = t_1 + i\Delta t$
Mathematical Definition	$g(t) = \frac{df}{dt}$ $= \lim_{\Delta t \rightarrow 0} \left( \frac{f(t + \Delta t) - f(t)}{\Delta t} \right)$	$f(t) - f(t_0) = \int_{t^*=t_0}^t g(t^*)dt^*$ $= \lim_{\Delta t \rightarrow 0} \left( \sum_{i=1}^n g(t_i)\Delta t \right)$
Geometric Interpretation	<p><math>\frac{df}{dt}</math> is the <i>slope</i> of the <math>f(t)</math> curve.</p>  <p>A graph with a vertical axis labeled <math>f(t)</math> and a horizontal axis labeled <math>t</math>. A curve is plotted, and a dashed line is tangent to it at a point. The word "tangent" is written next to the dashed line.</p>	<p><math>\int_{t^*=t_0}^t g(t^*)dt^*</math> is the <i>area</i> under the <math>g(t)</math> curve.</p>  <p>A graph with a vertical axis labeled <math>g(t^*)</math> and a horizontal axis labeled <math>t^*</math>. A curve is plotted, and the area under the curve between <math>t_0</math> and <math>t</math> is shaded. Dashed vertical lines connect the points <math>t_0</math> and <math>t</math> on the horizontal axis to the curve.</p>

## 4.6 Numerical Integration: Trapezoidal Rule



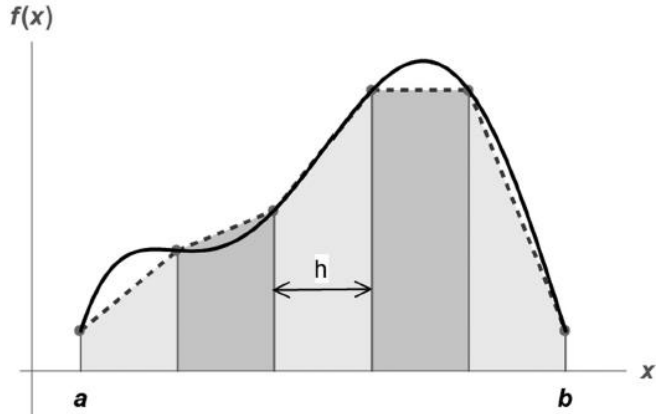
$$I = \int_{x=a}^b f(x) dx$$

- The *trapezoid rule* uses a linear interpolation to approximate  $f(x)$ . An integral using the trapezoid rule approximation is shown in Figure

$$I = \int_a^b f(x) dx \cong \int_a^b \left( f(a) + \frac{f(b) - f(a)}{b - a} (x - a) \right) dx$$

$$I \cong (b - a) \left( \frac{f(a) + f(b)}{2} \right)$$

## 4.6 Numerical Integration: Trapezoidal Rule



$$I = \int_a^b f(x) dx$$

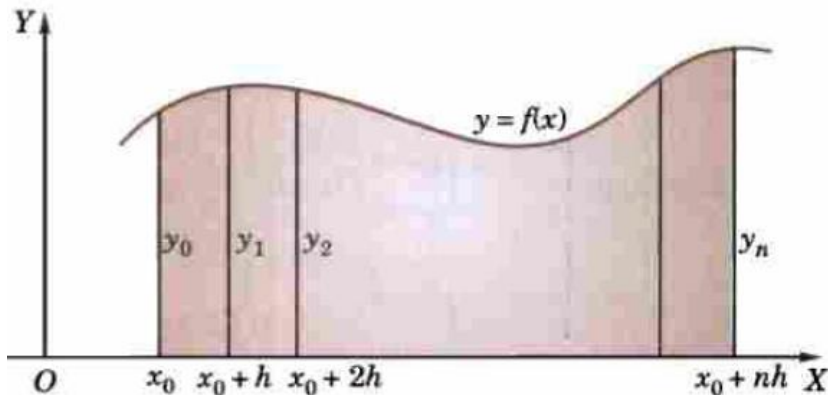
$$I = \int_a^b f(x) dx = \int_{x_0}^{x_1} f(x) dx + \int_{x_1}^{x_2} f(x) dx + \dots + \int_{x_{n-1}}^{x_n} f(x) dx$$

$$\cong b \frac{f(x_0) + f(x_1)}{2} + b \frac{f(x_1) + f(x_2)}{2} + \dots + b \frac{f(x_{n-1}) + f(x_n)}{2}$$

$$I \cong \frac{h}{2} \left( f(x_0) + 2 \sum_{i=1}^{n-1} f(x_i) + f(x_n) \right)$$

$$I = \underbrace{(b-a)}_{\text{width}} \underbrace{\frac{1}{2n} \left( f(x_0) + 2 \sum_{i=1}^{n-1} f(x_i) + f(x_n) \right)}_{\text{average height}}$$

$$E = -\frac{1}{12} (b-a) h^2 \bar{f}''$$



$$\int_{x_0}^{x_0+nh} f(x) dx = \frac{h}{2} [(y_0 + y_n) + 2(y_1 + y_2 + \dots + y_{n-1})]$$

## 4.6 Numerical Integration: Trapezoidal Rule (Example)

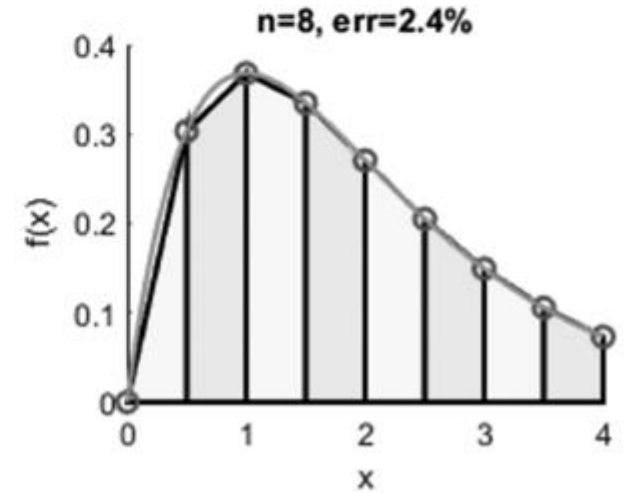
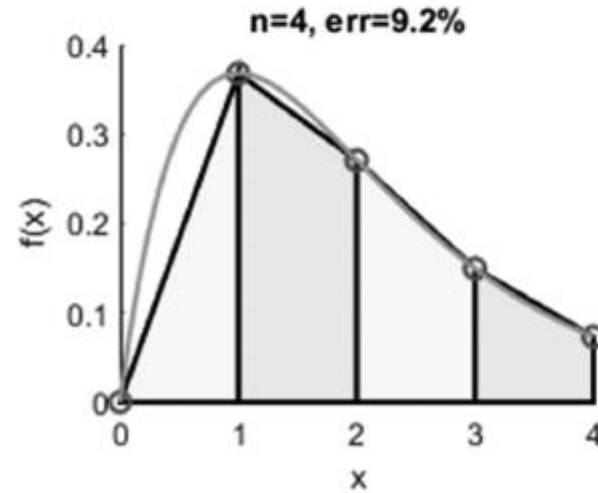
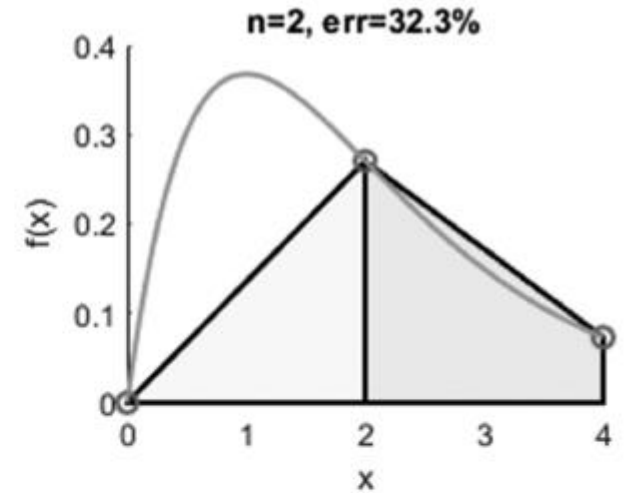
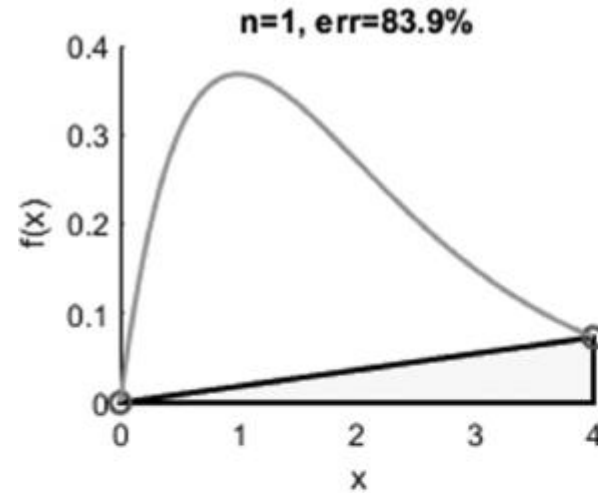
As an example, consider the integral

$$I = \int_{x=a}^b f(x) dx = \int_{x=a}^b xe^{-x} dx$$

In this case, the exact integral can be determined as

$$I_{\text{exact}} = \left(-xe^{-x} - e^{-x}\right)_{x=a}^{x=b} = \left(-be^{-b} - e^{-b}\right) - \left(-ae^{-a} - e^{-a}\right)$$

Choosing  $a=0$  and  $b=4$  gives  $I_{\text{exact}}=0.9084$ .



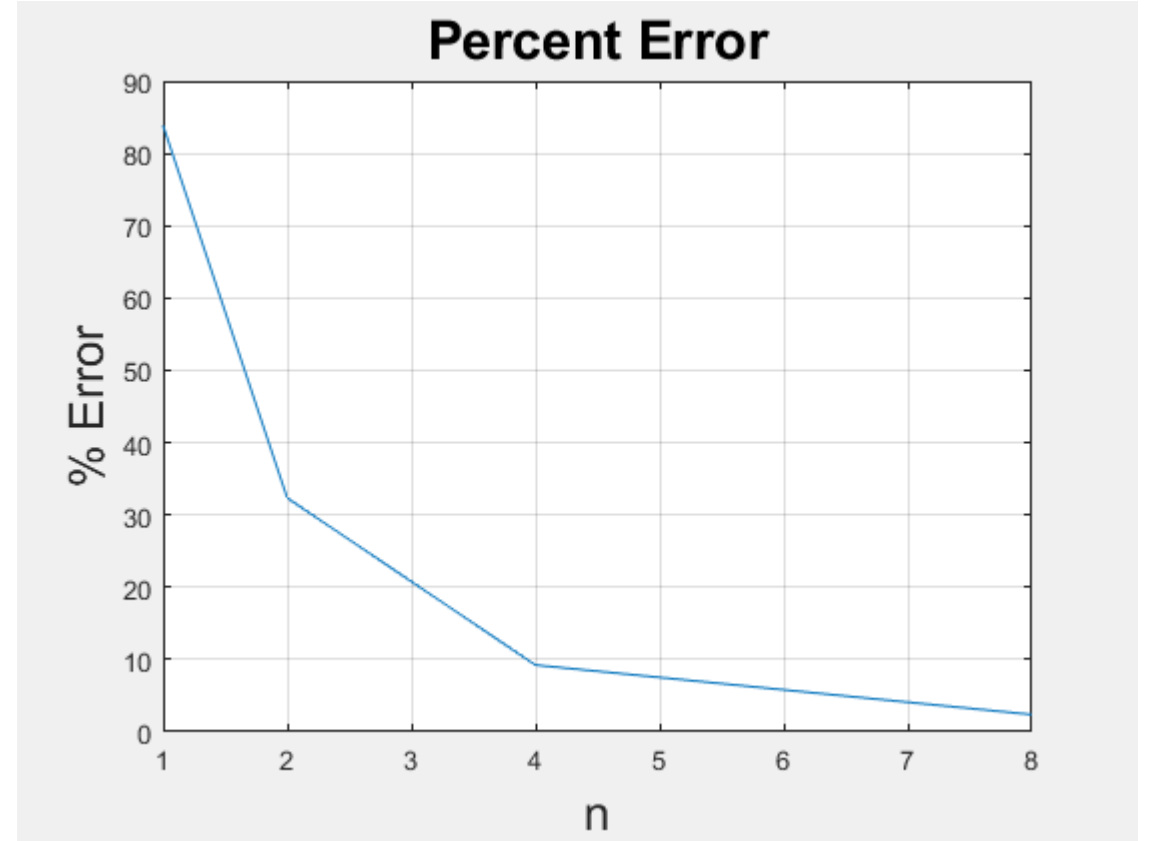
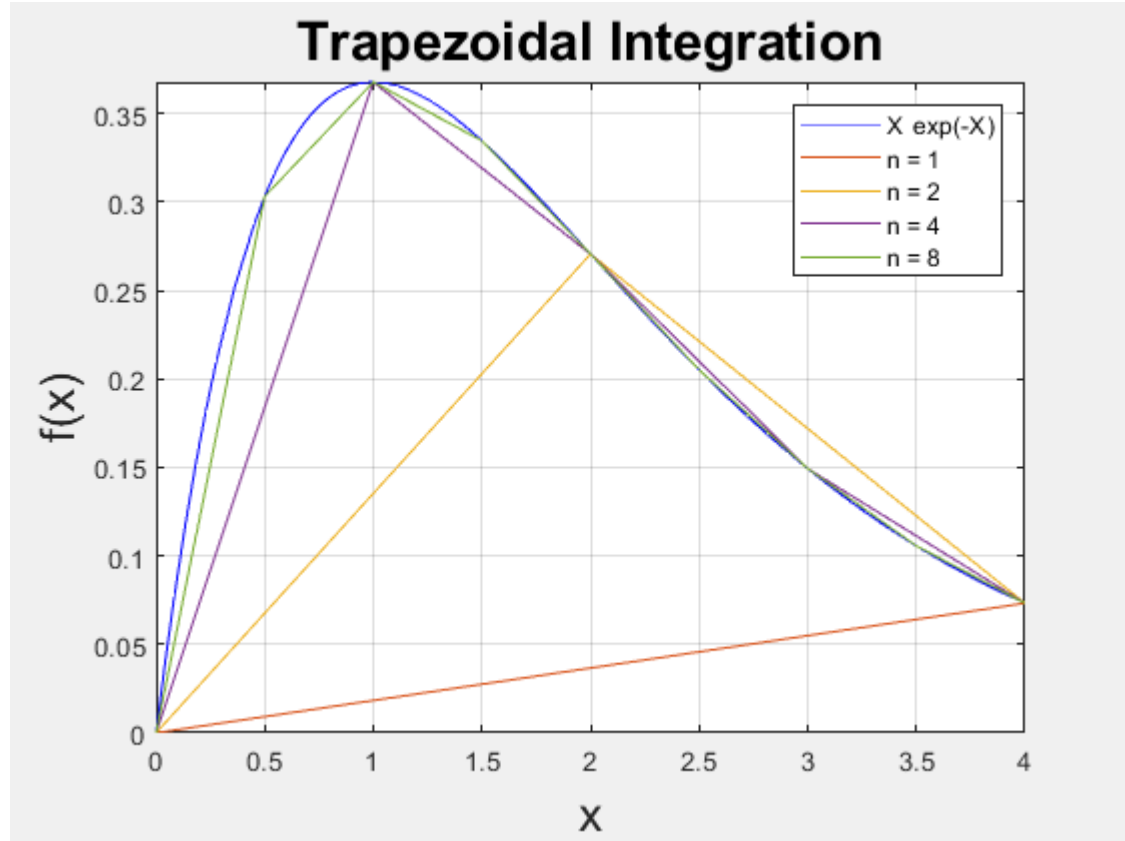
## 4.6 Numerical Integration: Trapezoidal Rule (Example)

```
% House Keeping
clc
clear
clear all

% Exact Function
syms X
a=0
b=4
n=[1;2;4;8]
exact=vpa(int(X.*exp(-X),a,b))
figure(1)
fplot(@(X) X*exp(-X),[a b],'b')
title('Trapezoidal Integration','FontSize',20); % Title
xlabel('x','FontSize',18); % Labels the x-axis
ylabel('f(x)','FontSize',18); % Labels the y-axis
grid; %Includes grid lines in the plot
hold on
```

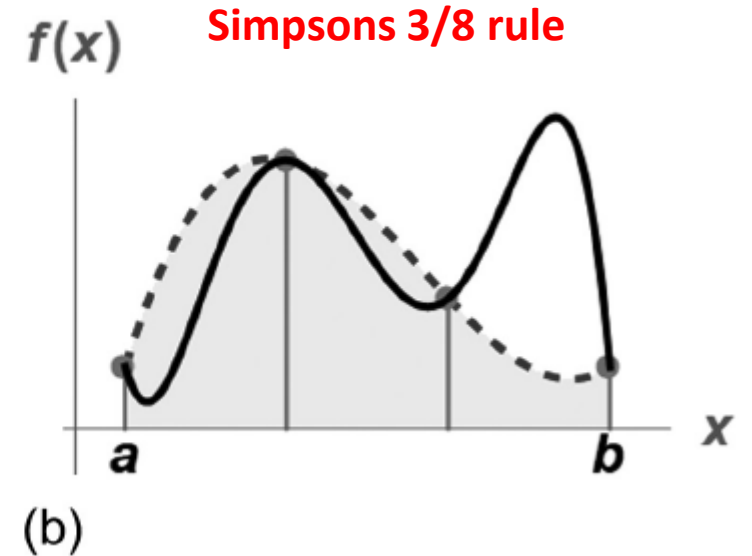
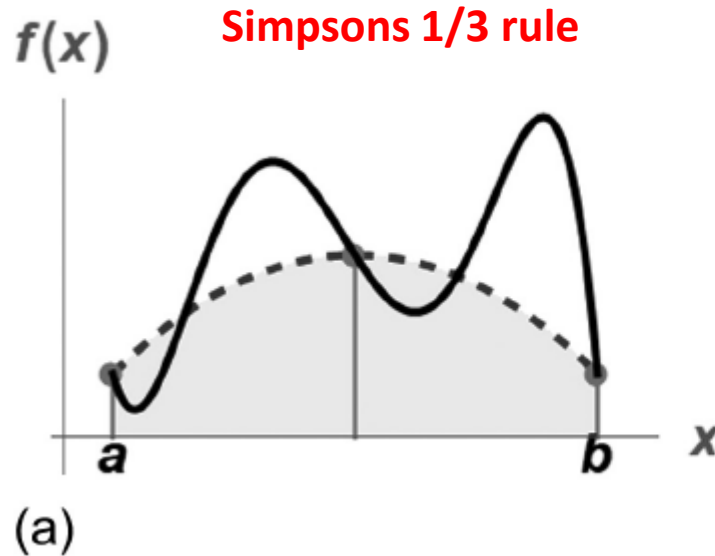
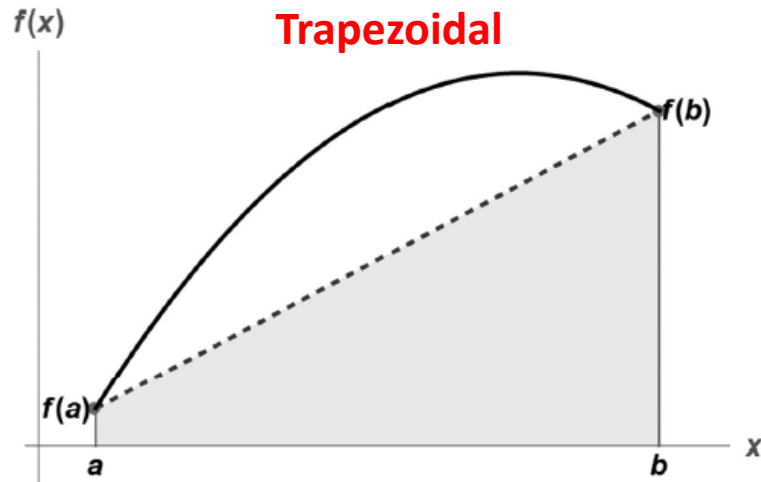
```
% Trapezoidal Rule
for i=1:max(size(n))
    x=[a:(b-a)/n(i):b]
    y=x.*exp(-x)
    txt = ['n = ',num2str(n(i))];
    plot(x,y,'DisplayName',txt)
    legend show
    I=trapz(x,y)
    error(i)=100*(exact-I)/exact
end
figure(2)
plot(n,error)
title('Percent Error','FontSize',20); % Title
xlabel('n','FontSize',18); % Labels the x-axis
ylabel('% Error','FontSize',18); % Labels the y-axis
grid; %Includes grid lines in the plot
```

## 4.6 Numerical Integration: Trapezoidal Rule (Example)



## 4.6 Numerical Integration: Simpsons one-third rule

- Instead of a linear interpolation as used with the trapezoid rule, Simpson's rules use higher-order polynomials. The quadratic and cubic interpolating functions are shown in the following Figure



$$\int_{x_0}^{x_0+nh} f(x) dx = \frac{h}{3} [(y_0 + y_n) + 4(y_1 + y_3) + \dots + y_{n-1}) + 2(y_2 + y_4 + \dots + y_{n-2})] \quad \text{Simpsons 1/3 rule}$$

$$I \cong \frac{h}{3} (f(x_0) + 4f(x_1) + f(x_2))$$

$$\int_{x_0}^{x_0+nh} f(x) dx = \frac{3h}{8} [(y_0 + y_n) + 3(y_1 + y_2 + y_4 + y_5 + \dots + y_{n-1}) + 2(y_3 + y_6 + \dots + y_{n-3})] \quad \text{Simpsons 3/8 rule}$$

$$I = \frac{3h}{8} (f(x_0) + 3f(x_1) + 3f(x_2) + f(x_3))$$



## 4.6 Numerical Integration: Example

- Evaluate  $\int_0^6 \frac{dx}{1+x^2}$  using a) Trapezoidal rule; b) Simpson's 1/3 rule; c) Simpson's 3/8 rule.

x	0	1	2	3	4	5	6
f(x)	1	1.5	0.2	0.1	0.05884	0.0385	0.027
y	y0	y1	y2	y3	y4	y5	y6

By Trapezoidal rule,

$$\begin{aligned}\int_0^6 \frac{1}{1+x^2} &= \frac{h}{2} [(y_0 + y_6) + 2(y_1 + y_2 + y_3 + y_4 + y_5)] \\ &= \frac{1}{2} [(1 + 0.027) + 2(0.5 + 0.2 + 0.1 + 0.0588 + 0.0385)] = 1.4108.\end{aligned}$$

By Simpson's 1/3 rule,

$$\begin{aligned}\int_0^6 \frac{1}{1+x^2} &= \frac{h}{3} [(y_0 + y_6) + 4(y_1 + y_3 + y_5) + 2(y_2 + y_4)] \\ &= \frac{1}{3} [(1 + 0.027) + 4(0.5 + 0.1 + 0.0385) + 2(0.2 + 0.0588)] = 1.3662.\end{aligned}$$

By Simpson's 3/8 rule,

$$\begin{aligned}\int_0^6 \frac{1}{1+x^2} &= \frac{3h}{8} [(y_0 + y_6) + 3(y_1 + y_2 + y_4 + y_5) + 2y_3] \\ &= \frac{3}{8} [(1 + 0.027) + 3(0.5 + 0.2 + 0.0588 + 0.0385) + 2(0.1)] = 1.3571.\end{aligned}$$

## 4.6 Numerical Integration: Example

- Evaluate  $\int_0^6 \frac{dx}{1+x^2}$  using a) Trapezoidal rule; b) Simpson's 1/3 rule; c) Simpson's 3/8 rule.

```
% House Keeping
```

```
clc
```

```
clear
```

```
clear all
```

```
% Exact Function
```

```
syms X
```

```
a=0
```

```
b=6
```

```
n=6
```

```
exact=vpa(int(1/(1+X.^2),a,b))
```

```
% Data
```

```
x=[a:(b-a)/n:b]
```

```
y=1./(1+x.^2)
```

```
% Trapezoidal
```

```
I_trap=trapz(x,y)
```

```
error_I_3_8=100*(exact-I_trap)/exact
```

```
% Simpson's 1/3
```

```
I_1_3=simpson(x,y,[],'1/3')
```

```
error_I_1_3=100*(exact-I_1_3)/exact
```

```
% Simpson's 3/8
```

```
I_3_8=simpson(x,y,[],'3/8')
```

```
error_I_3_8=100*(exact-I_3_8)/exact
```

```
I_trap =
```

```
1.4108
```

```
error_I_3_8 =
```

```
-0.36644546083921529896209780771262
```

```
I_1_3 =
```

```
1.3662
```

```
error_I_1_3 =
```

```
2.8082596776963738498539098910662
```

```
I_3_8 =
```

```
1.3571
```

```
error_I_3_8 =
```

```
3.455119987507605727249014490671
```

# References

- *Applied Engineering Mathematics*, Brian Vick, CRC Press, 2020
- *Numerical Methods in Engineering with MATLAB*, Jaan Klusalaas, Cambridge University Press, 2012